

YUMI IWASHITA

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RESEARCH INTERESTS

Computer vision for robotics applications, such as motion capture system using multiple cameras and people tracking system using cameras. Biometrics and pattern recognition for security systems, such as people recognition on both ground and aerial surveillance cameras. Medical image processing for the purpose of a navigation system for a surgical robot. Range data processing for building a huge-scale structure with multiple robots and people tracking.

EDUCATION

Kyushu University, Japan 2004-2007
Ph.D. Information Science and Electrical Engineering
"Motion Capture System Robust in Target Occlusion using Fast Level Set Method"

Kyushu University, Japan 2002-2004
M.S. Information Science and Electrical Engineering
"3D Shape Reconstruction using Fast Level Set Method"

WORK HISTORY

Visiting researcher, Jet Propulsion Laboratory, USA 2011-PRESENT
Assistant Professor, Kyushu University, Japan 2007-PRESENT
Visiting researcher, Imperial College London, UK 2007

RESEARCH EXPERIENCE

People tracking from aerial images OCT 2011-PRESENT
Visiting researcher, Jet Propulsion Laboratory
Research began at JPL with Dr. Curtis Padgett. The goal is to track people from aerial images robustly to occlusion, noise, and parallax.

People recognition from shadow biometrics 2009-PRESENT
Assistant Professor, Kyushu University
Visiting researcher, Jet Propulsion Laboratory
Research began in collaboration with Dr. Adrian Stoica at JPL and has continued. The goal is to recognize people from their shadows for the purpose of wide area security operations.

People recognition from gait 2007-PRESENT
Visiting Researcher, Imperial College London (till Sep. on 2007)
Assistant Professor, Kyushu University
Research began at Imperial College London in collaboration with Prof. Maria Petrou and has continued. The goal is to recognize people under various changes, such as appearance changes and walking on curved trajectories. Methods to synthesize images adaptively from 3D walking models has been developed.

3D modeling of large-scale architectural structures with multiple robots 2007-2011
Assistant Professor, Kyushu University
Research was undertaken at Kyushu University with Prof. Kurazume. The goal was to develop an automatic 3-D laser measurement system of an environmental structure using the cooperation of multiple mobile robots.

Classification of vehicles using a laser range finder 2009-2010
Assistant Professor, Kyushu University
Research was undertaken at Kyushu University with Prof. Kurazume. The goal was to develop a system to identify in real time the kind of the vehicles (car, bike, bus...) and in the special case of buses to read the company name.

Target tracking using laser range finders 2007-2010
Assistant Professor, Kyushu University
Research was undertaken at Kyushu University with Prof. Kurazume. The goal was to develop a system to track multiple people with distributed laser range finders and cameras.

3D reconstruction of a femoral shape using 2D fluoroscopic images 2007-2009
Assistant Professor, Kyushu University
Research was undertaken at Kyushu University in collaboration with Prof. Sato at Osaka University. The goal was to develop a system to reconstruct precise 3D shapes of living organisms or bones from a few conventional 2D fluoroscopic images.

Fast 2D-3D Registration for Navigation System of Surgical Robot 2005-2006
Graduate student researcher, Kyushu University
Research was undertaken at Kyushu University with Prof. Kurazume. The goal was to superimpose a tumor model on an endoscopic image precisely.

2D-3D alignment based on geometrical consistency 2005-2006
Graduate student researcher, Kyushu University
Research was undertaken at Kyushu University with Prof. Hara. The goal was to develop a system to align a 3D geometrical model to a 2D image, which is robust for initial registration errors, for reconstructing a realistic 3D model of indoor scene settings.

Motion capture system using multiple cameras 2003-2007
Graduate student researcher, Kyushu University
Research was undertaken at Kyushu University with Prof. Kurazume. The goal was to reconstruct 3D models of multiple people in real-time. In this system the Fast Level Set Method was applied to stereo range data captured by multiple stereo cameras.

AWARDS and HONORS

Postdoctoral Fellowships for Research Abroad, Japan Society for the Promotion of Science 2011-PRESENT
Jet Propulsion Laboratory, USA

T.J.Tarn Best Paper in Robotics, 2010 IEEE Int. Conf. on Robotics and Biomimetics (ROBIO 2012), China 2010

Best Oral Presentation Award , Int. Conf. on Emerging Security Technologies (EST 2010), UK 2010

Best Oral Presentation Award, Image and Vision Computing New Zealand 2008

Postdoctoral Fellowships for Young Scientists, Japan Society for the Promotion of Science 2007
Imperial College London, UK

IEEE Robotics and Automation Society Japan Chapter Young Award 2005

GRANT

- [G1] **Grant-in-Aid for Scientific Research (C), Japan Society for the Promotion of Science** 2011-2013
Principal Investigator
Gait recognition system using invisible lights
- [G2] **Grant-in-Aid for Scientific Research (B), Japan Society for the Promotion of Science** 2011-2013
Researcher
Development of 3D scanning system using multiple robots
- [G3] **Grant-in-Aid for Scientific Research (B), Japan Society for the Promotion of Science** 2010-2012
Researcher
Supporting Robotic Activities in Informationally Structured Environment
- [G4] **Project for Future Generation Robots, New Energy and Industrial Technology Development Organization** 2010-2012
Researcher
Development of Informationally Structured Environment for robots
- [G5] **Grant-in-Aid for Scientific Research (B), Japan Society for the Promotion of Science** 2009-2010
Principal Investigator
Motion capture system using parametric 3D shape model
- [G6] **Grant A-Step, Japan Science and Technology Agency** 2009
Principal Investigator
Gait recognition robust to appearance changes using 4D gait database
- [G7] **Project for Intelligent Medical Robots, New Energy and Industrial Technology Development Organization** 2007-2010
Co-Investigator
Development of Endoscopic Operation Robot

PUBLICATIONS

Journals

- [J1] Y. Iwashita, A. Stoica, and R. Kurazume, "Gait identification using shadow biometrics", *Pattern Recognition Letters*, 2012 (to appear) 2012
- [J2] Y. Tobata, R. Kurazume, Y. Noda, K. Lingemann, Y. Iwashita, T. Hasegawa, "Laser-based geometrical modeling of large-scale architectural structures using co-operative multiple robots", *Autonomous Robot*, Vol.32, No.1, pp. 49-62, (2012) 2012
- [J3] S. Oishi, R. Kurazume, Y. Iwashita, T. Hasegawa, " Smoothing Range Image using Trilateral Filter and Reflectance Image", *Journal of the Institute of Electrical Engineering of Japan*, Vol.132, No.2, Sec.C, pp.291-298, (2012) (in Japanese) 2012
- [J4] J. Yongjin, Y. Iwashita, R. Kurazume, "Study on CPS-SLAM Improvement of Measurement Precision and Application for Tunnel Shape Measurement System", *Journal of the Robotics Society of Japan*, Vol.30, No.2, pp.180-187, (2012) (in Japanese) 2012
- [J5] A. Tamura, K. Morooka, R. Kurazume, Y. Iwashita, "Trachea and Esophagus Classification by AdaBoost", *Journal of the Institute of Electronics, Information and Communication Engineers*, Vol.J92-D, No.12, pp.2249-2260, (2010) (in Japanese) 2010
- [J6] R. Kurazume, H. Yamada, K. Sokabe, K. Murakami, Y. Iwashita, T. Hasegawa, "Simultaneous Tracking of Multiple Targets Using SIR/MCMC Particle Filters by Distributed Cameras and Laser Range Finders", *Journal of the Robotics Society of Japan*, Vol.27, No.1, pp.65-76, (2010) (in Japanese) 2010
- [J7] R. Kurazume, K. Nakamura, O. Okada, Y. Sato, N. Sugano, T. Koyama, Y. Iwashita, T. Hasegawa, "3D reconstruction of a femoral shape using a parametric model and two 2D fluoroscopic images", *Computer Vision and Image Understanding*, vol.113, no.2, pp.202-211, 2009 2009
- [J8] Y. Kabashima, K. Hara, R. Kurazume, Y. Iwashita, K. Morooka, S. Uchida, T. Hasegawa, "2D/3D Registration by Back Projection and Geometrical Constraints", *Journal of the Institute of Electronics, Information and Communication Engineers*, Vol.J91-D, No.5, pp.1380-1392, (2008) (in Japanese) 2008
- [J9] Y. Iwashita, R. Kurazume, K. Konishi, M. Nakamoto, N. Aburaya, Y. Sato, M. Hashizume, T. Hasegawa, "Fast Model-Image Registration using 2D Distance Map for Surgical Navigation System", *Advanced Robotics*, Vol.21 No.7, pp.751-770, 2007 2007
- [J10] Y. Iwashita, R. Kurazume, K. Hara, S. Uchida, K. Morooka, T. Hasegawa, "Fast 3D Shape Reconstruction of Moving Objects by Parallel Fast Level Set Method", *Journal of the Institute of Electronics, Information and Communication Engineers*, Vol.J90-D, No. 8, pp.1888-1899, (2007) (in Japanese) 2007

- [J11] Y. Iwashita, R. Kurazume, T. Tsuji, K. Hara, T. Hasegawa, "3D Tracking of Multiple Moving Objects using Fast Level Set Method", *Journal of the Robotics Society of Japan*, Vol.23, No.7, pp.813-820, (2005) (in Japanese) 2005
- [J12] Y. Iwashita, R. Kurazume, S. Konishi, M. Nakamoto, M. Hashizume, T. Hasegawa, "Fast Alignment of 3D Geometrical Models and 2D Grayscale Images Using 2D Distance Maps", *Journal of Institute of Electronics, Information and Communication Engineers*, Vol.J88-D-II, No.9, pp.1889-1899, (2005) (in Japanese) 2005
- [J13] R. Kurazume, S. Yui, T. Tsuji, Y. Iwashita, K. Hara, T. Hasegawa, "Fast Level Set Method and Realtime Tracking of Moving Objects in a Sequence of Images", *Journal of the Information Processing Society of Japan*, Vol.44, No.8, pp.2244-2254, (2003) (in Japanese) 2003
- Selected Refereed Conference Papers (12 papers out of 30 papers)**
- [C1] Y. Iwashita, K. Uchino, R. Kurazume, A. Stoica, "Gait identification from invisible shadows", *SPIE Biometric Technology for Human Identification IX*, 2012. 2012
- [C2] Y. Iwashita, R. Baba, K. Ogawara, R. Kurazume, "Method for gait-based biometric identification robust to changes in observation angle", *26th International Conference Image and Vision Computing New Zealand*, 2011 2011
- [C3] R. Kurazume, Y. Iwashita, K. Murakami, and T. Hasegawa, "Introduction to the Robot Town Project and 3-D Co-operative Geometrical Modeling Using Multiple Robots", *International Symposium on Robotics Research*, 2011 2011
- [C4] Y. Iwashita, A. Stoica, R. Kurazume, "Person Identification using Shadow Analysis", *British Machine Vision Conference*, pp.35.1--10, 2010 2010
- [C5] Y. Iwashita, R. Baba, K. Ogawara, R. Kurazume, "Person identification from spatio-temporal 3D gait", *Int. Conf. on Emerging Security Technologies*, pp.30-35, 2010 2010
- [C6] Y. Iwashita, R. Kurazume, T. Mori, M. Saito and T. Hasegawa, "Model-based motion tracking system using distributed network cameras", *IEEE Int. Conf. on Robotics and Automation*, pp.3020-3025, 2010. 2010
- [C7] Y. Iwashita and R. Kurazume, "Person identification from human walking sequences using affine moment invariants", *IEEE Int. Conf. on Robotics and Automation*, 2009 2009
- [C8] Y. Iwashita and M. Petrou, "Person identification from spatio-temporal volumes", *Int. Conf. Image and Vision Computing New Zealand*, 2008 2008
- [C9] Y. Iwashita, R. Kurazume, K. Hara, S. Uchida, K. Morooka, and T. Hasegawa, "Fast 3D Reconstruction of Human Shape and Motion Tracking by Parallel Fast Level Set Method", *IEEE Int. Conf. on Robotics and Automation*, pp.980-986, 2008 2008

- [C10] Y. Iwashita, R. Kurazume, K. Nakamura, T. Okada, Y. Sato, N. Sugano, T. Koyama, T. Hasegawa, "Patient-specific femoral shape estimation using a parametric model and two 2D fluoroscopic images", *ACCV'07 Workshop on Multi-dimensional and Multi-view Image Processing*, MM-O-9, 2007
- [C11] Y. Iwashita, R. Kurazume, K. Hara, T. Hasegawa, "Robust Motion Capture System against Target Occlusion using Fast Level Set Method", *IEEE Int. Conf. on Robotics and Automation*, pp.168-174, 2006
- [C12] Y. Iwashita, R. Kurazume, K. Konishi, M. Nakamoto, M. Hashizume, T. Hasegawa, "Fast 2D-3D Registration for Navigation System of Surgical Robot", *IEEE Int. Conf. on Robotics and Automation*, pp.909-915, 2005

PROFESSIONAL ACTIVITIES

Associate Editor

- [AE1] International Conference on Intelligent Robots and Systems (IROS 2012) 2012
- [AE2] Symposium on Image Recognition and Understanding 2011 (Japanese) 2011

Executive Committee

- [EC1] IEEE Japan Council Women in Engineering 2010-PRESENT

Program Committee

- [PC1] International Conference Image and Vision Computing New Zealand 2012
- [PC2] IEEE International Conference on Robotics and Biomimetics (ROBIO) 2012
- [PC3] International Workshop on Depth Image Analysis 2012
- [PC4] International Conference on Emerging Security Technologies (EST) 2012
- [PC5] IEEE International Conference on Robotics and Biomimetics (ROBIO) 2011
- [PC6] International Conference on Intelligent Robotics and Applications (ICIRA) 2011
- [PC7] China-Japan-Korea Joint Workshop on Pattern Recognition (CJKPR2010) 2010
- [PC8] International Conference on Intelligent Robotics and Applications (ICIRA) 2010
- [PC9] Asian Conference on Computer Vision (ACCV) 2010
- [PC10] IEEE International Conference on Robotics and Biomimetics (ROBIO) 2010
- [PC11] Advanced Technologies for Enhanced Quality of Life (AT-EQUAL) 2010
- [PC12] International Conference on Emerging Security Technologies (EST) 2010
- [PC13] International Workshop on Human Behavior Sensing (HBS) 2010
- [PC14] ECSIS Symposium on Learning and Adaptive Behavior in Robotic Systems 2010

Reviewer for Journals

- [RJ1] Elsevier, Engineering Applications of Artificial Intelligence 2012
- [RJ2] Journal of the Institute of Electronics, Information and Communication Engineers 2008-PRESENT
- [RJ3] Journal of Control, Measurement, and System Integration 2012
- [RJ4] Advanced Robotics 2010-PRESENT
- [RJ5] IEEE Trans. On Systems, Man and Cybernetics - Part B 2010
- [RJ6] Elsevier, Medical Image Analysis 2010

Reviewer for Conferences

- [RC1] International Conference on Robotics and Automation (ICRA'13) 2013
- [RC2] International Conference on Robotics and Automation (ICRA'12) 2012
- [RC3] IEEE International Conference on Pattern Recognition (ICPR'12) 2012
- [RC4] International Conference on Robotics and Automation (ICRA'11) 2011
- [RC5] Asian Conference on Computer Vision (ACCV'10) 2010
- [RC6] Asian Conference on Computer Vision (ACCV'09) 2009