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EDUCATION

Tokyo Institute of Technology, Japan 1998
Ph.D. Department of Mechanical Engineering Science
"Study on Cooperative Positioning System"

Tokyo Institute of Technology, Japan 1989-1991
M.S. Department of Mechanical Engineering Science
"Motion Control of Free Flying Robot with Dual-Arms"

WORK HISTORY

Vice Dean, Faculty of Information Science and Electrical Engineering, Kyushu University 2016- PRESENT

Professor, Faculty of Information Science and Electrical Engineering, Kyushu University 2007- PRESENT

Associate Professor, Faculty of Information Science and Electrical Engineering, Kyushu University 2002-2007

Research Scientist, Institute of Industrial Science, University of Tokyo 2000-2002

Research Associate, Department of Mechanical Engineering Science Tokyo Institute of Technology 1995-2000

Researcher Fujitsu Laboratories LTD 1991-1994

SOCIETIES and ACTIVITIES

The Robotics Society of Japan 1989-PRESENT
The Japan Society of Mechanical Engineers 1995-PRESENT
The Information Processing Society of Japan 2001-PRESENT
The Society of Instrument and Control Engineers 2004-PRESENT
The Institute of Electronics, Information and Communication Engineers 2006-PRESENT

IEEE-RAS	2006-PRESENT
Director of the Robotics Society of Japan (RSJ)	2013-2015
Director of the Society of Instrument and Control Engineers (SICE)	2013-2015
Director of the Robotics Society of Japan (RSJ)	2009-2011

AWARDS and HONORS

Fellow of RSJ	2016
SICE System Integration Division Research Award	2015
EST 2014 Best Paper in the Machine Vision Workshop	2014
RSJ Best Paper Award	2014
14th Symposium on Construction Robotics in Japan Best Paper Award	2014
JSME Robotics and Mechatronics Academic Achievement Award	2012
Best Paper Award Candidate in Robotics Symposia	2010
IEEE ROBIO T.J.Tarn Best Paper in Robotics	2010
ICEST Best Paper Award	2010
JSME Robotics and Mechatronics Award	2009
RSJ Service Award	2008
RSJ Best Paper Award	1993
JSME Hatakeyama Award	1989

GRANT

Grant-in-Aid for Challenging Exploratory Research Japan Society for the Promotion of Science Principal Investigator	2016-2017
Grant-in-Aid for Scientific Research (A) Japan Society for the Promotion of Science Principal Investigator	2014-2017
Grant-in-Aid for Challenging Exploratory Research Japan Society for the Promotion of Science Principal Investigator	2014-2015
COI-STREAM (Center of Innovation Science and Technology based Radical Innovation and Entrepreneurship Program) Ministry of Education, Culture, Sports, Science and Technology Researcher	2013-2021
Grant-in-Aid for Challenging Exploratory Research Japan Society for the Promotion of Science Principal Investigator	2012-2013
Strategic Information and Communications R&D Promotion Programme	2012-2015

Ministry of Internal Affairs and Communications
Researcher

Grant-in-Aid for Scientific Research (B) 2011-2013
Japan Society for the Promotion of Science
Principal Investigator

Grant-in-Aid for Scientific Research (B) 2010-2012
Japan Society for the Promotion of Science
Principal Investigator

A-Step (Adaptable and Seamless Technology Transfer Program 2010-2010
through Target-driven R&D
Japan Science and Technology Agency
Principal Investigator

Grant-in-Aid for Scientific Research Investigation 2009-2010
Japan Society for the Promotion of Science
Principal Investigator

Grant-in-Aid for Research on Construction Technology 2009-2010
Ministry of Land, Infrastructure, Transport and Tourism
Principal Investigator

Project to Develop "Innovative Seeds" 2008-2008
Japan Science and Technology Agency
Principal Investigator

Project for Future Generation Robots 2007-2012
New Energy and Industrial Technology Development Organization
Researcher

Project for Intelligent Medical Robots 2007-2010
New Energy and Industrial Technology Development Organization
Researcher

Grant-in-Aid for Scientific Research (B) 2007-2009
Japan Society for the Promotion of Science
Principal Investigator

Strategic Development of Advanced Robotics Elemental Technologies 2006-2008
New Energy and Industrial Technology Development Organization
Researcher

Grant-in-Aid for Scientific Research (B) 2006-2008
Japan Society for the Promotion of Science
Researcher

Grant-in-Aid for Research and Development Fukuoka Industry, Science and Technology Foundation Principal Investigator	2006-2006
Grant-in-Aid for Scientific Research (A) Japan Society for the Promotion of Science Researcher	2005-2008
Special Coordination Funds for Promoting Science and Technology, Ministry of Education, Culture, Sports, Science and Technology Researcher	2005-2007
Grant-in-Aid for Young Scientists (B), Japan Society for the Promotion of Science Principal Investigator	2004-2005
Strategic Information and Communications R&D Promotion Programme, Ministry of Internal Affairs and Communications Researcher	2003-2005
Grant-in-Aid for Scientific Research (A), Japan Society for the Promotion of Science Researcher	2002-2004
Grant-in-Aid for Young Scientists , Japan Society for the Promotion of Science Principal Investigator	1998-1999
Grant-in-Aid for Young Scientists, Japan Society for the Promotion of Science Principal Investigator	1996-1996

PUBLICATIONS

International Journals (30 papers)

Automatic large-scale three dimensional modeling using cooperative multiple robots
Ryo Kurazume, Souichiro Oshima, Shingo Nagakura, Yongjin Jeong, Yumi Iwashita
Computer Vision and Image Understanding, Vol., No., pp., 2016 (accepted)

Local N-ary Patterns: a local multi-modal descriptor for place categorization
Hojung Jung, Oscar Martinez Mozos, Yumi Iwashita, Ryo Kurazume
Advanced Robotics, Vol. 30, No. 6, pp. 402--415, 2016, doi:10.1080/01691864.2015.1120242

Service Robot System with an Informationally Structured Environment
Yoonseok Pyo, Kouhei Nakashima, Shunya Kuwahata, Ryo Kurazume, Tokuo Tsuji, Ken'ichi

Morooka, Tsutomu Hasegawa
Robotics and Autonomous Systems, Vol.74, No.Part A, pp. 148--165, 2015,
doi:10.1016/j.robot.2015.07.010

The Informationally Structured Room for Robotic Assistance
Tokuo Tsuji, Oscar Martinez Mozos, Hyunuk Chae, YoonSeok Pyo, Kazuya Kusaka, Tsutomu Hasegawa, Ken'ichi Morooka, Ryo Kurazume
Sensors, Vol.15, No.4, pp.9438--9465, 2015, doi:10.3390/s150409438

Manual/Automatic Colorization for Three-Dimensional Geometric Models utilizing Laser Reflectivity
Shuji Oishi, Ryo Kurazume
Advanced Robotics, Vol.28, No.24, pp.1617--1635, 2014, doi:10.1080/01691864.2014.968616

Identification of people walking along curved trajectories
Yumi Iwashita, Koichi Ogawara, Ryo Kurazume
Pattern Recognition Letters, Vol.48, No.15, pp.60--69, 2014, doi:10.1016/j.patrec.2014.04.004

Floor Sensing System using Laser Reflectivity for Localizing Everyday Objects and Robot
Yoonseok Pyo, Tsutomu Hasegawa, Tokuo Tsuji, Ryo Kurazume, Ken'ichi Morooka
Sensors, Vol.14, No.4, pp. 7524--7540, 2014, doi:10.3390/s140407524

Gait-based person identification robust to changes in appearance
Yumi Iwashita, Koji Uchino, Ryo Kurazume
Sensors, Vol.13, No.6, pp.7884--7901, 2013, doi:10.3390/s130607884

Categorization of Indoor Places by Combining Local Binary Pattern Histograms of Range and Reflectance Data from Laser Range Finders
Oscar Martinez Mozos, Hitoshi Mizutani, Hojung Jung, Ryo Kurazume, Tsutomu Hasegawa
Advanced Robotics, Vol.27, No.18, pp.1455--1464, 2013

Range Image Smoothing and Completion utilizing Laser Intensity
Shuji Oishi, Ryo Kurazume, Yumi Iwashita, Tsutomu Hasegawa
Advanced Robotics, Vol.27, No.12, pp.947--958, 2013

Robust Visual Servoing for Object Manipulation against Temporary Loss of Sensory Information using a Multi-Fingered Hand-Arm
Akihiro Kawamura, Kenji Tahara, Ryo Kurazume, Tsutomu Hasegawa
Journal of Robotics and Mechatronics, Vol.25, No.1, pp.125--135, 2013

Robust global localization using laser reflectivity
Dong Xiang ZHANG, Ryo Kurazume, Yumi Iwashita, Tsutomu Hasegawa
Journal of Robotics and Mechatronics, Vol.25, No.1, pp.38--52, 2013

Dynamic Grasping of an Arbitrary Polyhedral Object
Akihiro Kawamura, Kenji Tahara, Ryo Kurazume, Tsutomu Hasegawa
Robotica, Vol.31, No.4, pp. 511--523, 2013

Development of 3D scanning system using automatic guiding total station

Ken Endou, Takafumi Ikenoya, Ryo Kurazume

Journal of Robotics and Mechatronics, Vol.24, No.6, pp.992--999, 2012

Gait identification using shadow biometrics

Yumi Iwashita, Adrian Stoica, Ryo Kurazume

Pattern Recognition Letters, Vol.33, No.16, pp.2148--2155, 2012

Categorization of Indoor Places Using the Kinect Sensor

Oscar Martinez Mozos, Hitoshi Mizutani, Ryo Kurazume, Tsutomu Hasegawa

Sensors, Vol.12, No.5, pp.6695--6711, 2012

Laser-based geometrical modeling of large-scale architectural structures using co-operative multiple robots

Yukihiro Tobata, Ryo Kurazume, Yusuke Noda, Kai Lingemann, YumiIwashita, Tsutomu Hasegawa

Autonomous Robot, Vol.32, No.1, pp. 49--62, 2012

HELIOS Tracked Robot Team: Mobile RT System for Special Urban Search and Rescue Operations

Ryuichi Hodoshima, Michele Guarnieri, Ryo Kurazume, Hiroshi Masuda, Takao Inoh, Paulo Debenest, Eduardo F. Fukushima, Shigeo Hirose

Journal of Robotics and Mechatronics, Vol.23, No.6, pp.1041--1054, 2011

Multi-Part People Detection Using 2D Range Data

Oscar Martinez Mozos, Ryo Kurazume, Tsutomu Hasegawa

International Journal of Social Robotics, Vol.2, No.1, pp.31--40, 2010

A Decision Method for Placement of Tactile Elements on a Sensor Glove for the Recognition of Grasp Types

Kouji Murakami, Kazuya Matsuo, Tsutomu Hasegawa, and Ryo Kurazume

IEEE/ASME Transactions on Mechatronics, Vol.15, No.1, pp.157--162, 2010

Supporting Robotic Activities in Informationally Structured Environment with Distributed Sensors and RFID Tags

Kouji Murakami, Tsutomu Hasegawa, Ryo Kurazume, and Yoshihiko Kimuro

Journal of Robotics and Mechatronics, Vol.21, No.4, pp.453--459, 2009

3D reconstruction of a femoral shape using a parametric model and two 2D fluoroscopic images

Ryo Kurazume, Kaori Nakamura, Toshiyuki Okada, Yoshinobu Sato, Nobuhiko Sugano, Tsuyoshi Koyama, Yumi Iwashita, Tsutomu Hasegawa

Computer Vision and Image Understanding, Vol.113, No.2, pp. 202--211, 2009

Hierarchical face cluster partitioning of polygonal surfaces and high-speed rendering

Tokuo Tsuji, Hongbin Zha, Tsutomu Hasegawa, Ryo Kurazume

Systems and Computers in Japan, Vol.38, No.8, pp.32--43, 2007

Fast Model-Image Registration using 2D Distance Map for Surgical Navigation System

Yumi Iwashita, Ryo Kurazume, Kozo Konishi, Masahiko Nakamoto, Naoki Aburaya, Yoshinobu Sato, Makoto Hashizume, Tsutomu Hasegawa

Advanced Robotics, Vol.21, No.7, pp751--770, 2007

The Great Buddha Project: Digitally Archiving, Restoring, and Analyzing Cultural Heritage Objects
Katsushi Ikeuchi, Takeshi Oishi, Jun Takamatsu, Ryusuke Sagawa, Atsushi Nakazawa, Ryo Kurazume, No Nishino, Mawo Kamakura
International Journal of Computer Vision, Vol.75, No.1, pp.189--208, 2007

A New Index of Serial Link Manipulator Performance Combining Dynamic Manipulability and Manipulating Force Ellipsoids
Ryo Kurazume, Tsutomu Hasegawa
IEEE Transactions on Robotics, Vol.22, No.5, pp.1022--1028, 2006

Mapping textures on 3D geometric model using reflectance image
Ryo Kurazume, Ko Nishino, Mark D. Wheeler, Katsushi Ikeuchi
Systems and Computers in Japan, Vol.36, No.13, pp.92--101, 2005

Feedforward and feedback dynamic trot gait control for quadruped walking vehicle
Ryo Kurazume, Kan Yoneda, and Shigeo Hirose
Autonomous Robots, Vol.12, No.2, pp.157--172, 2002

Development of a Cleaning Robot System with Cooperative Positioning System
Ryo Kurazume, Shigeo Hirose
Autonomous Robots, Vol.9, No.3, pp. 237--246, 2000

An Experimental Study of a Cooperative Positioning System
Ryo Kurazume, Shigeo Hirose
Autonomous Robots, Vol.8, No.1, pp. 43--52, 2000

Domestic Journals in Japan (52 papers)

Selected Refereed Conference Papers (15 papers out of 136 papers)

Feasibility study of IoRT platform "Big Sensor Box"
Ryo Kurazume, Yoonseok Pyo, Tokuo Tsuji, and Akihiro Kawamura
Proc. IEEE International Conference on Robotics and Automation (ICRA2017), 2017

Multi-modal Panoramic 3D Outdoor Datasets for Place Categorization
Hojung Jung, Yuki Oto, Oscar Mozos, Yumi Iwashita, Ryo Kurazume
Proc. of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2016), pp.4545-4550, 2016

Automatic planning of laser measurements for a large-scale environment using CPS-SLAM system
Souichiro Oshima, Shingo Nagakura, Yongjin Jeong, Yumi Iwashita, Ryo Kurazume
Proc. of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2015), pp.4437-4444, 2015

Grasp Stability Evaluation based on Energy Tolerance in Potential Field
Tokuo Tsuji, Kosei Baba, Kenji Tahara, Kensuke Harada, Ken'ichi Morooka, Ryo Kurazume

Proc. of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2015), pp.2311-2316, 2015

Grasp Planning for Constricted Parts of Objects Approximated with Quadric Surfaces
Tokuo Tsuji, Soichiro Uto, Kensuke Harada, Ryo Kurazume, Tsutomu Hasegawa, Ken'ichi Morooka
2014 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2014), pp.2447-2453, 2014

First-Person Animal Activity Recognition from Egocentric Videos
Yumi Iwashita, Asamichi Takamine, Ryo Kurazume, Michael S. Ryoo
22nd International Conference on Pattern Recognition (ICPR 2014), pp.4310-4315, 2014

Colorization of 3D Geometric Model utilizing Laser Reflectivity
Shuji Oishi, Ryo Kurazume, Yumi Iwashita, Tsutomu Hasegawa
in Proc. IEEE International Conference on Robotics and Automation (ICRA 2013), pp.2311-2318, 2013

Iterative Learning Control for a Musculoskeletal Arm: Utilizing Multiple Space Variables to Improve the Robustness
Kenji Tahara, Yuta Kuboyama, Ryo Kurazume
Proc. of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2012), pp.4620-4625, 2012

Robust Visual Servoing for Object Manipulation with Large Time-Delays of Visual Information
Akihiro Kawamura, Kenji Tahara, Ryo Kurazume, Tsutomu Hasegawa
Proc. of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2012), pp.4797-4803, 2012

Position Tracking and Recognition of Everyday Objects by using Sensors Embedded in an Environment and Mounted on Mobile Robots
Kouji Murakami, Kazuya Matsuo, Tsutomu Hasegawa, Ryo Kurazume
in Proc. IEEE International Conference on Robotics and Automation (ICRA2012), pp., 2012

Denosing of Range Images using a Trilateral Filter and Belief Propagation
Shuji Oishi, Ryo Kurazume, Yumi Iwashita, Tsutomu Hasegawa
2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2011), pp.2020-2027, 2011

Robust Manipulation for Temporary Lack of Sensory Information by a Multi-Fingered Hand-Arm System
Akihiro Kawamura, Kenji Tahara, Ryo Kurazume, Tsutomu Hasegawa
2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2011), pp.4201-4206, 2011

Introduction to the Robot Town Project and 3-D Co-operative Geometrical Modeling Using Multiple Robots
Ryo Kurazume, Yumi Iwashita, Koji Murakami, Tsutomu Hasegawa
15th International Symposium on Robotics Research (ISRR 2011), pp., 2011

A Tactile Sensing for Estimating the Position and Orientation of a Joint-Axis of a Linked Object
Kazuya Matsuo, Kouji Murakami, Tsutomu Hasegawa, Ryo Kurazume
2010 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS10), pp.1884-1889, 2010

Position Tracking System for Commodities in a Daily Life Environment
Kouji Murakami, Tsutomu Hasegawa, Yasunobu Nohara, Byong-won Ahn, Ryo Kurazume
2010 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS10), pp.3712-3718, 2010

Domestic Conference Papers in Japan (403 papers)

Books/Chapters (6 books/chapters)

Invited Journal Papers (4 papers)

Invited Conference Papers/Talks (13)